

Outline

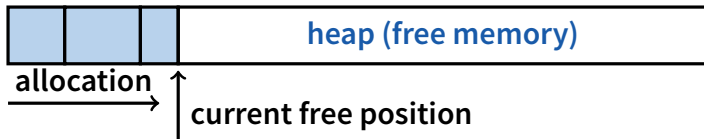
- 1 Malloc and fragmentation
- 2 Exploiting program behavior
- 3 Allocator designs
- 4 Garbage collection

Dynamic memory allocation

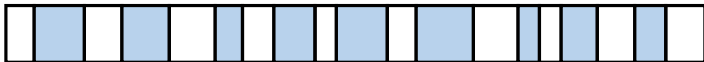
- **Almost every useful program uses it**
 - Gives wonderful functionality benefits
 - ▷ Don't have to statically specify complex data structures
 - ▷ Can have data grow as a function of input size
 - ▷ Allows recursive procedures (stack growth)
 - But, can have a huge impact on performance
- **Today: how to implement it**
 - Lecture based on [Wilson 1995]
- **Some interesting facts:**
 - Two or three line code change can have huge, non-obvious impact on how well allocator works (examples to come)
 - Proven: impossible to construct an "always good" allocator
 - Surprising result: after 35 years, memory management still poorly understood

Why is it hard?


- Satisfy arbitrary set of allocation and frees.
- Easy without free: set a pointer to the beginning of some big chunk of memory (“heap”) and increment on each allocation:

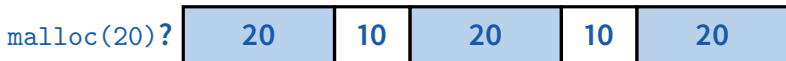


- Problem: free creates holes (“fragmentation”)
Result? Lots of free space but cannot satisfy request!



More abstractly

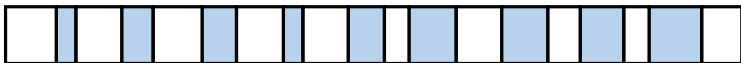
- **What an allocator must do?**  **freelist**
 - Track which parts of memory in use, which parts are free
 - Ideal: no wasted space, no time overhead
- **What the allocator cannot do?**
 - Control order of the number and size of requested blocks
 - Know the number, size, & lifetime of future allocations
 - Move allocated regions (bad placement decisions permanent)



- **The core fight: minimize fragmentation**
 - App frees blocks in any order, creating holes in “heap”
 - Holes too small? cannot satisfy future requests

What is fragmentation really?

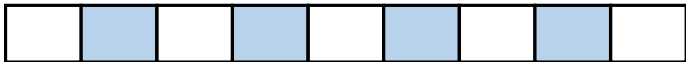
- Inability to use memory that is free
- Two factors required for fragmentation
 1. Different lifetimes—if adjacent objects die at different times, then fragmentation:



- ▶ If all objects die at the same time, then no fragmentation:

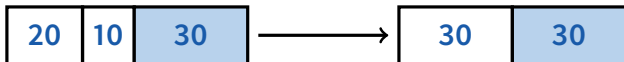


2. Different sizes: If all requests the same size, then no fragmentation (that's why no external fragmentation with paging):



Important decisions

- **Placement choice: where in free memory to put a requested block?**
 - Freedom: can select any memory in the heap
 - Ideal: put block where it won't cause fragmentation later (impossible in general: requires future knowledge)
- **Split free blocks to satisfy smaller requests?**
 - Fights internal fragmentation
 - Freedom: can choose any larger block to split
 - One way: choose block with smallest remainder (best fit)
- **Coalescing free blocks to yield larger blocks**



- Freedom: when to coalesce (deferring can save work)
- Fights external fragmentation

Impossible to “solve” fragmentation

- **If you read allocation papers to find the best allocator**
 - All discussions revolve around tradeoffs
 - The reason? There cannot be a best allocator
- **Theoretical result:**
 - For any possible allocation algorithm, there exist streams of allocation and deallocation requests that defeat the allocator and force it into severe fragmentation.
- **How much fragmentation should we tolerate?**
 - Let M = bytes of live data, n_{\min} = smallest allocation, n_{\max} = largest – How much gross memory required?
 - Bad allocator: $M \cdot (n_{\max}/n_{\min})$
 - ▷ E.g., only ever use a memory location for a single size
 - ▷ E.g., make all allocations of size n_{\max} regardless of requested size
 - Good allocator: $\sim M \cdot \log(n_{\max}/n_{\min})$

Pathological examples

- **Suppose heap currently has 7 20-byte chunks**



- What's a bad stream of frees and then allocates?
- **Given a 128-byte limit on malloced space**
 - What's a really bad combination of mallocs & frees?
- **Next: two allocators (best fit, first fit) that, in practice, work pretty well**
 - "pretty well" = $\sim 20\%$ fragmentation under many workloads

Pathological examples

- **Suppose heap currently has 7 20-byte chunks**



- What's a bad stream of frees and then allocates?
- Free every other chunk, then alloc 21 bytes
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Pathological examples

- **Suppose heap currently has 7 20-byte chunks**

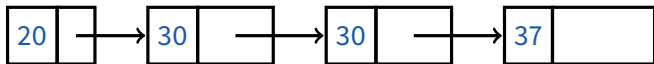
| | | | | | | |
|----|----|----|----|----|----|----|
| 20 | 20 | 20 | 20 | 20 | 20 | 20 |
|----|----|----|----|----|----|----|

- What's a bad stream of frees and then allocates?
- Free every other chunk, then alloc 21 bytes
- **Given a 128-byte limit on malloced space**
 - What's a really bad combination of mallocs & frees?
 - Malloc 128 1-byte chunks, free every other
 - Malloc 32 2-byte chunks, free every other (1- & 2-byte) chunk
 - Malloc 16 4-byte chunks, free every other chunk...
- **Next: two allocators (best fit, first fit) that, in practice, work pretty well**
 - "pretty well" = $\sim 20\%$ fragmentation under many workloads

Best fit

- **Strategy: minimize fragmentation by allocating space from block that leaves smallest fragment**

- Data structure: heap is a list of free blocks, each has a header holding block size and a pointer to the next block

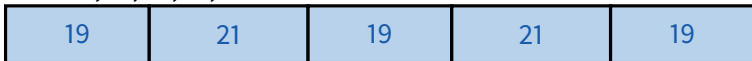


- Code: Search freelist for block closest in size to the request. (Exact match is ideal)
 - During free (usually) coalesce adjacent blocks
- **Potential problem: Sawdust**
 - Remainder so small that over time left with “sawdust” everywhere
 - Fortunately not a problem in practice

Best fit gone wrong

- **Simple bad case: allocate n, m ($n < m$) in alternating orders, free all the n s, then try to allocate an $n + 1$**
- **Example: start with 99 bytes of memory**

- alloc 19, 21, 19, 21, 19



- free 19, 19, 19:



- alloc 20? Fails! (wasted space = 57 bytes)
- **However, doesn't seem to happen in practice**

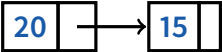
First fit

- **Strategy: pick the first block that fits**
 - Data structure: free list, sorted LIFO, FIFO, or by address
 - Code: scan list, take the first one
- **LIFO: put free object on front of list.**
 - Simple, but causes higher fragmentation
 - Potentially good for cache locality
- **Address sort: order free blocks by address**
 - Makes coalescing easy (just check if next block is free)
 - Also preserves empty/idle space (locality good when paging)
- **FIFO: put free object at end of list**
 - Gives similar fragmentation as address sort, but unclear why


Subtle pathology: LIFO FF

- **Storage management example of subtle impact of simple decisions**
- **LIFO first fit seems good:**
 - Put object on front of list (cheap), hope same size used again (cheap + good locality)
- **But, has big problems for simple allocation patterns:**
 - E.g., repeatedly intermix short-lived $2n$ -byte allocations, with long-lived $(n + 1)$ -byte allocations
 - Each time large object freed, a small chunk will be quickly taken, leaving useless fragment. Pathological fragmentation

First fit: Nuances

- **First fit sorted by address order, in practice:**
 - Blocks at front preferentially split, ones at back only split when no larger one found before them
 - Result? Seems to roughly sort free list by size
 - So? Makes first fit operationally similar to best fit: a first fit of a sorted list = best fit!
- **Problem: sawdust at beginning of the list**
 - Sorting of list forces a large requests to skip over many small blocks. Need to use a scalable heap organization
- **Suppose memory has free blocks:** 
 - If allocation ops are 10 then 20, best fit wins
 - When is FF better than best fit?

First fit: Nuances

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 - If allocation ops are 10 then 20, best fit wins
 - When is FF better than best fit?
 - Suppose allocation ops are 8, 12, then 12 \implies first fit wins

Some worse ideas

- **Worst-fit:**

- Strategy: fight against sawdust by splitting blocks to maximize leftover size
- In real life seems to ensure that no large blocks around

- **Next fit:**

- Strategy: use first fit, but remember where we found the last thing and start searching from there
- Seems like a good idea, but tends to break down entire list

- **Buddy systems:**

- Round up allocations to power of 2 to make management faster
- Result? Heavy internal fragmentation
- Used in virtual address space allocation

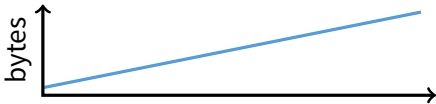
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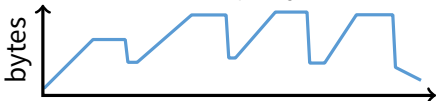
Known patterns of real programs

- So far we've treated programs as black boxes.
- Most real programs exhibit 1 or 2 (or all 3) of the following patterns of alloc/dealloc:

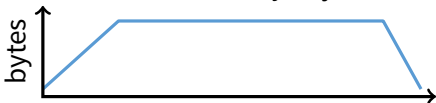
- *Ramps*: accumulate data monotonically over time



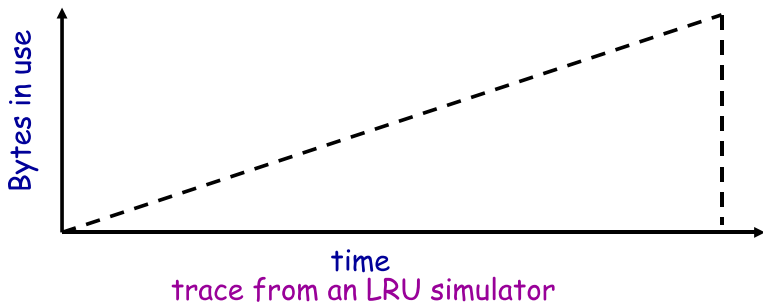
- *Peaks*: allocate many objects, use briefly, then free all



- *Plateaus*: allocate many objects, use for a long time

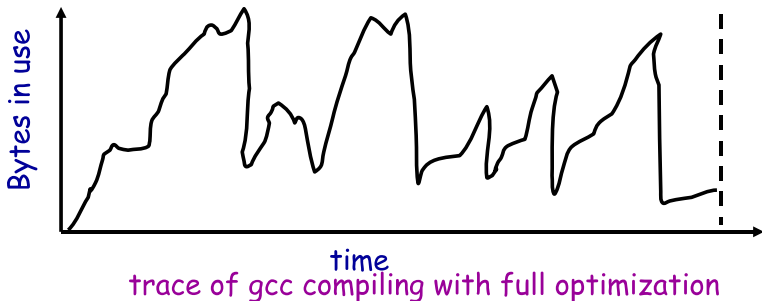


Pattern 1: ramps



- **In a practical sense: ramp = no free!**
 - Implication for fragmentation?
 - What happens if you evaluate allocator with ramp programs only?

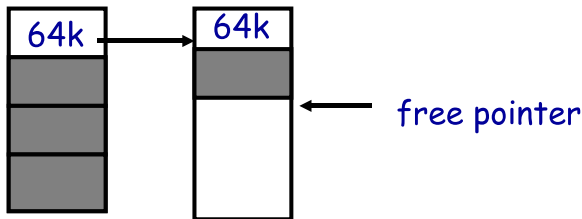
Pattern 2: peaks



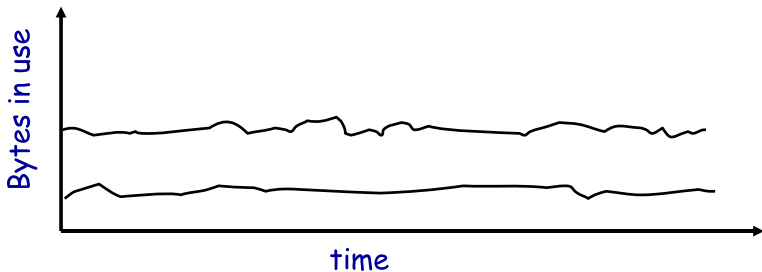
- **Peaks: allocate many objects, use briefly, then free all**
 - Fragmentation a real danger
 - What happens if peak allocated from contiguous memory?
 - Interleave peak & ramp? Interleave two different peaks?

Exploiting peaks

- **Peak phases: allocate a lot, then free everything**
 - Change allocation interface: allocate as before, but only support free of everything all at once
 - Called “arena allocation”, “obstack” (object stack), or `alloca`/procedure call (by compiler people)
- **Arena = a linked list of large chunks of memory**
 - Advantages: alloc is a pointer increment, free is “free”
No wasted space for tags or list pointers



Pattern 3: Plateaus



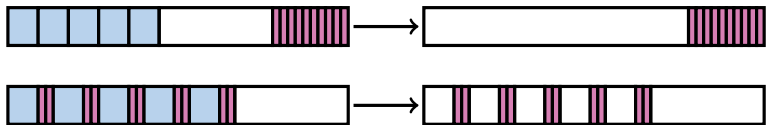
trace of perl running a string processing script

- **Plateaus: allocate many objects, use for a long time**
 - What happens if overlap with peak or different plateau?

Fighting fragmentation

- **Segregation = reduced fragmentation:**

- Allocated at same time ~ freed at same time
- Different type ~ freed at different time



- **Implementation observations:**

- Programs allocate a small number of different sizes
- Fragmentation at peak usage more important than at low usage
- Most allocations small (< 10 words)
- Work done with allocated memory increases with size
- Implications?

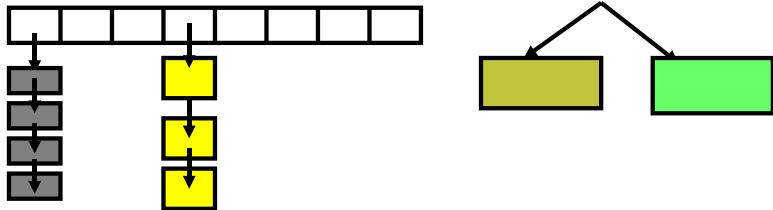
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Slab allocation [Bonwick]

- **Kernel allocates many instances of same structures**
 - E.g., a 1.7 KB `task_struct` for every process on system
- **Often want contiguous *physical* memory (for DMA)**
- **Slab allocation optimizes for this case:**
 - A **slab** is multiple pages of contiguous physical memory
 - A **cache** contains one or more slabs
 - Each cache stores only one kind of object (fixed size)
- **Each slab is full, empty, or partial**
- **E.g., need new `task_struct`?**
 - Look in the `task_struct` cache
 - If there is a partial slab, pick free `task_struct` in that
 - Else, use empty, or may need to allocate new slab for cache
- **Advantages: speed, and no internal fragmentation**

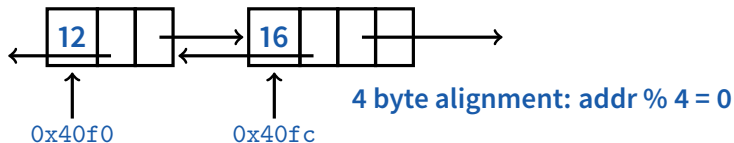
Simple, fast segregated free lists



- **Array of free lists for small sizes, tree for larger**
 - Place blocks of same size on same page
 - Have count of allocated blocks: if goes to zero, can return page
- **Pro: segregate sizes, no size tag, fast small alloc**
- **Con: worst case waste: 1 page per size even w/o free, After pessimal free: waste 1 page per object**
- **TCMalloc [[Ghemawat](#)] is a well-documented malloc like this**

Typical space overheads

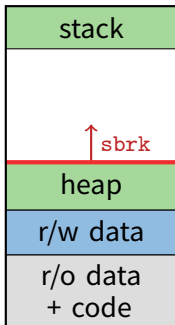
- Free list bookkeeping and alignment determine minimum allocatable size:
- If not implicit in page, must store size of block
- Must store pointers to next and previous freelist element



- **Allocator doesn't know types**
 - Must align memory to conservative boundary
- **Minimum allocation unit? Space overhead when allocated?**

Getting more space from OS

- On Unix, can use `sbrk`
 - E.g., to activate a new zero-filled page:



```
/* add nbytes of valid virtual address space */  
void *get_free_space(size_t nbytes) {  
    void *p = sbrk(nbytes);  
    if (!p)  
        error("virtual memory exhausted");  
    return p;  
}
```

- For large allocations, `sbrk` a bad idea
 - May want to give memory back to OS
 - Can't with `sbrk` unless big chunk last thing allocated
 - So allocate large chunk using `mmap`'s `MAP_ANON`

Buddy Allocator Example

- Variations still used as the basis of other designs
- Used to allocate virtual address space
- Process:
 - Allocate memory rounded to the closest power of 2
 - If no memory exists of that size split a larger memory region
 - Repeat until we have the size we want
- Allocations: 2, 1, 4, 8, ...

15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



Free

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| | | | |
|-------|------|------|------|
| Alloc | Free | Free | Free |
|-------|------|------|------|

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| | | | | | | | | | | | |
|-------|---|---|------|--|--|--|------|--|--|--|--|
| Alloc | A | F | Free | | | | Free | | | | |
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| | | | | |
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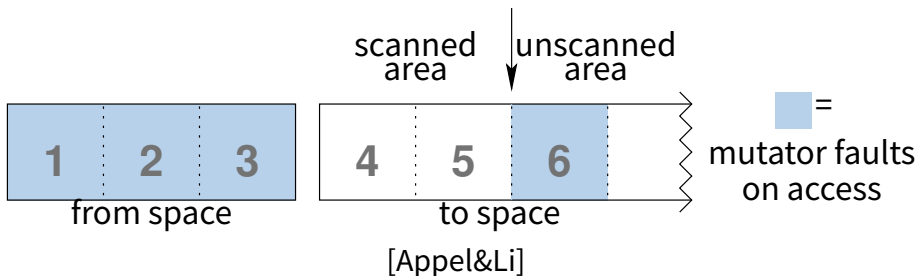
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Garbage collection

- **In safe languages, run time knows about all pointers**
 - So can move an object if you change all the pointers
- **What memory locations might a program access?**
 - Any objects whose pointers are currently in registers
 - Recursively, any pointers in objects it might access
 - Anything else is *unreachable*, or *garbage*; memory can be re-used
- **Example: stop-and-copy garbage collection**
 - Memory full? Temporarily pause program, allocate new heap
 - Copy all objects pointed to by registers into new heap
 - ▷ Mark old copied objects as copied, record new location
 - Start scanning through new heap. For each pointer:
 - ▷ Copied already? Adjust pointer to new location
 - ▷ Not copied? Then copy it and adjust pointer
 - Free old heap—program will never access it—and continue

Concurrent garbage collection

- **Idea: Stop & copy, but without the stop**
 - *Mutator* thread runs program, *collector* concurrently does GC
- **When collector invoked:**
 - Protect from space & unscanned to space from mutator
 - Copy objects in registers into *to space*, resume mutator
 - All pointers in scanned *to space* point to *to space*
 - If mutator accesses unscanned area, fault, scan page, resume



Heap overflow detection

- **Many GCed languages need fast allocation**
 - E.g., in lisp, constantly allocating cons cells
 - Allocation can be as often as every 50 instructions
- **Fast allocation is just to bump a pointer**

```
char *next_free;
char *heap_limit;

void *alloc (unsigned size) {
    if (next_free + size > heap_limit) /* 1 */
        invoke_garbage_collector (); /* 2 */
    char *ret = next_free;
    next_free += size;
    return ret;
}
```

- **But would be even faster to eliminate lines 1 & 2!**

Heap overflow detection 2

- **Mark page at end of heap inaccessible**
 - `mprotect (heap_limit, PAGE_SIZE, PROT_NONE);`
- **Program will allocate memory beyond end of heap**
- **Program will use memory and fault**
 - Note: Depends on specifics of language
 - But many languages will touch allocated memory immediately
- **Invoke garbage collector**
 - Must now put just allocated object into new heap
- **Note: requires more than just resumption**
 - Faulting instruction must be resumed
 - But must resume with different target virtual address
 - Doable on most architectures since GC updates registers

Reference counting

- **Seemingly simpler GC scheme:**

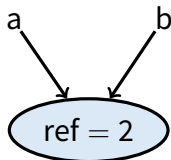
- Each object has “ref count” of pointers to it
- Increment when pointer set to it
- Decrement when pointer killed
(C++ destructors handy—c.f. `shared_ptr`)

```
void foo(bar c) {  
    bar a b;  
    a = c;    // c.refcnt++  
    b = a;    // a.refcnt++  
    a = 0;    // c.refcnt--  
    return;  // b.refcnt--  
}
```

- ref count == 0? Free object

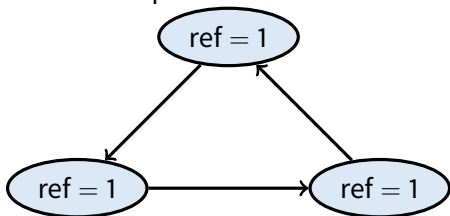
- **Works well for hierarchical data structures**

- E.g., pages of physical memory



Reference counting pros/cons

- **Circular data structures always have ref count > 0**
 - No external pointers means **lost memory**



- **Can do manually w/o PL support, but error-prone**
- **Potentially more efficient than real GC**
 - No need to halt program to run collector
 - Avoids weird unpredictable latencies
- **Potentially less efficient than real GC**
 - With real GC, copying a pointer is cheap
 - With refcounts, must update count each time & possibly take lock (but C++11 `std::move` can avoid overhead)

Ownership types

- **Another approach: avoid GC by exploiting type system**
 - Use ownership types, which prohibit copies
- **You can move a value into a new variable (e.g., copy pointer)**
 - But then the original variable is no longer usable
- **You can *borrow* a value by creating a pointer to it**
 - But must prove pointer will not outlive borrowed value
 - And can't use original unless both are read-only (to avoid races)
- **Ownership types available now in new language **Rust****
 - First serious competitor to C/C++ for OSes, browser engines
- **C++11 does something similar but weaker with unique types**
 - `std::unique_ptr`, `std::unique_lock`,...
 - Can `std::move` but not copy these